LOIS - High-Performance Computing for a Distributed Space Probing Sensor Network

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LCSC 18 - 19 October, 2004

Science

- IRF (Swedish Institute of Space Physics)
- LOIS Space Centre
- Växjö University
- Uppsala DataBase Labaratory

Companies

- Videum Science Park, Växjö
- AerotechTelub AB, Växjö
- IBM

Outline



Outline



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Main principles Principles in Practice

Outline



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Main principles Principles in Practice

Specialisation

Specialised people for special tasks

Dynamic

Continuous development

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Main principles Principles in Practice

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Main principles Principles in Practice

3D LOIS Cube



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Deep Space RADAR

Outline



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Deep Space RADAR

VENUS - 3 MM CONTINUUM EMISSION



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Space physics

- Passive mapping
- Active mapping
- Dynamical system Active and passive

Deep Space RADAR

Space physics

- Passive mapping
- Active mapping
- Dynamical system Active and passive



Deep Space RADAR





Space physics

- Passive mapping
- Active mapping
- Dynamical system Active and passive

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Deep Space RADAR





Astronomy

Interstellar

• Intergalactic

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Deep Space RADAR

Astronomy

- Interstellar
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Analog system Digital Systems

Outline



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Analog system Digital Systems

The Past

- Specialised equipment
- Storage and transport
- Static/mechanical solutions



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Analog system Digital Systems

Outline



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Analog system Digital Systems

Tomorrow

- Using off the shelf equipment
- Smarter sensors
- Software instead of hardware upgrades



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Receiving signals Transmitting signals Comparing signals

Challenges

- Receiving Signals
- Transmitting signals
 Comparing signals



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Receiving signals Transmitting signals Comparing signals

Outline

 Main principles Principles in Practice Space Analog Digital 5 Hi-performance computing Receiving signals

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Receiving signals Transmitting signals Comparing signals



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Receiving signals Transmitting signals Comparing signals

Data

- Each antenna node gives 1Gb/s (6Gb/s)
- Ca. 10 000 nodes grouped in sub grids
- Sub grid distributed over the whole of southern Sweden



Receiving signals Transmitting signals Comparing signals

Data

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Receiving signals Transmitting signals Comparing signals

LOFAR and LOIS sites

Data

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Receiving signals Transmitting signals Comparing signals

Receiving

- Realtime and post processing of data
- Recalibration and compensation of changing environment
- Multiple simultaneous experiments



Receiving signals Transmitting signals Comparing signals

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Receiving signals Transmitting signals Comparing signals

Outline

 Main principles Principles in Practice Space Analog Digital 5 Hi-performance computing Receiving signals Transmitting signals

Receiving signals Transmitting signals Comparing signals

Transmitting

- High number of possible transmitting modes and combinations
- By using receiving and transmitting sub arrays we can correct the transmitting signal in real time.



Receiving signals Transmitting signals Comparing signals

Transmitting

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Receiving signals Transmitting signals Comparing signals



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Comparing

- Analytical results
- Simulations

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Receiving signals Transmitting signals Comparing signals



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Comparing

- Analytical results
- Simulations

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Receiving signals Transmitting signals Comparing signals

Kinetic simulations





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Transmitting signals **Comparing signals**

Kinetic simulations

 $\frac{\partial f_{\alpha}}{\partial t} + \mathbf{v} \cdot \nabla f_{\alpha} + \frac{\mathbf{q}_{\alpha}}{\mathbf{m}_{\alpha}} \left(\mathbf{E} + \mathbf{v} \times \mathbf{B} \right) \cdot \nabla_{\mathbf{v}} f_{\alpha} = \mathbf{0}$

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$$\begin{aligned} \nabla \cdot E &= \frac{\rho}{\epsilon_0} \\ \nabla \cdot B &= 0 \\ \nabla \times E &= -\frac{\partial B}{\partial t} \\ \nabla \times B &= \mu_o j + \frac{1}{c^2} \frac{\partial E}{\partial t} \end{aligned}$$



-31

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Challenges

- adaptability and heterogeneity
- Heractic hardware clustering
- Real time calculations



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